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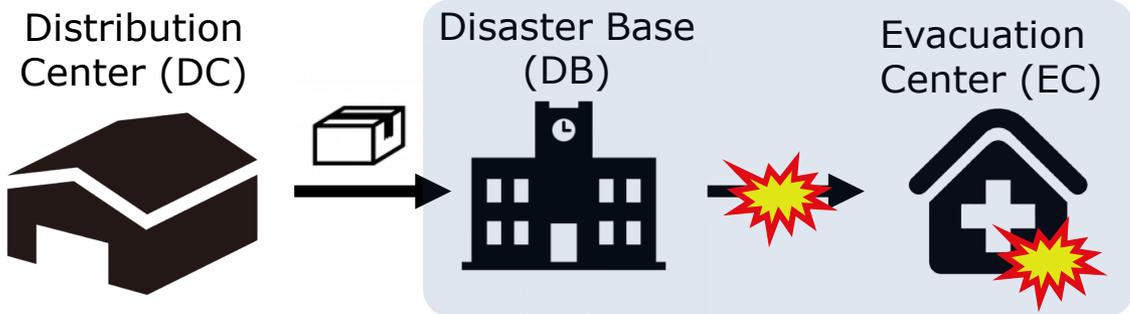
Optimization of inventory transportation strategy, considering the procurement of goods by the affected population

21st Summer Course
Behavior Modeling in Transportation Networks

Tokyo Institute of Technology

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Background



Relief Goods Transportation Network

- Humanitarian Organizations (HOs; e.g., governments) need to supply relief goods to ECs.

Bad Reports³⁾ (Examples)

- Surge Demand ^{causes} → Queue Congestion
- Supply Constraints ^{causes} → Inventory Congestion

Should rethink relief goods flow



(a) Queue by rationing ¹⁾



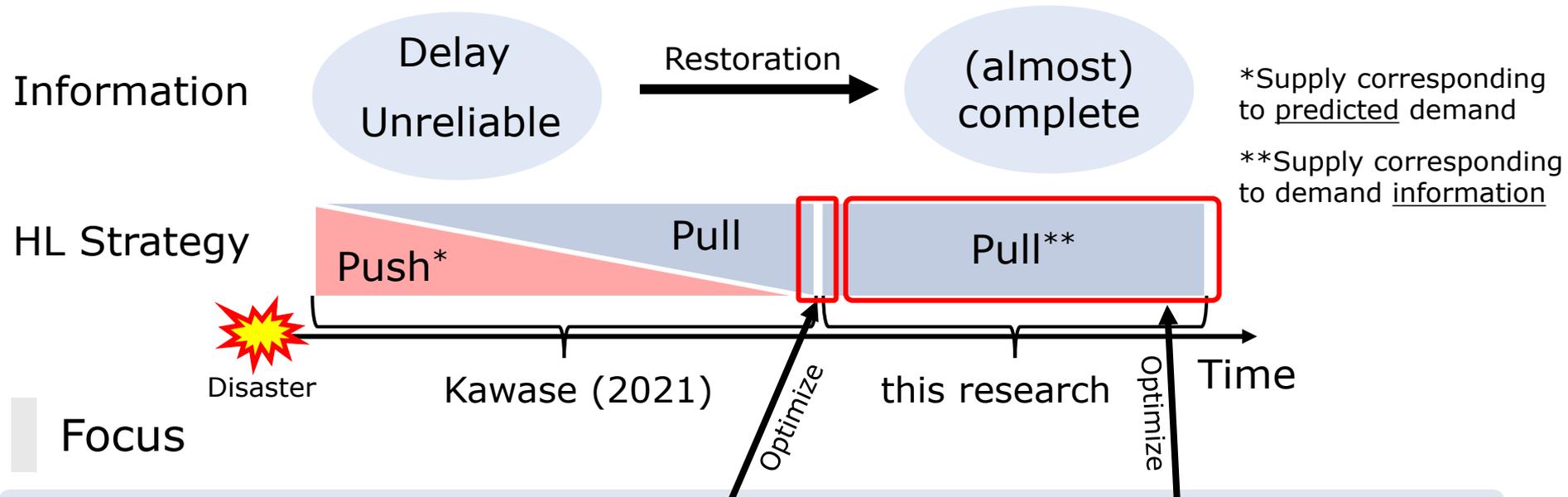
(b) Inventory congestion ²⁾

Humanitarian Logistics (HL)

Definition

“ the process of planning, implementing and controlling **the efficient, cost-effective flow and storage of goods and materials, as well as related information**, from the point of origin to the point of consumption for the purpose of alleviating the suffering of vulnerable people. ”

HL with restoration process of **Information** Infrastructure



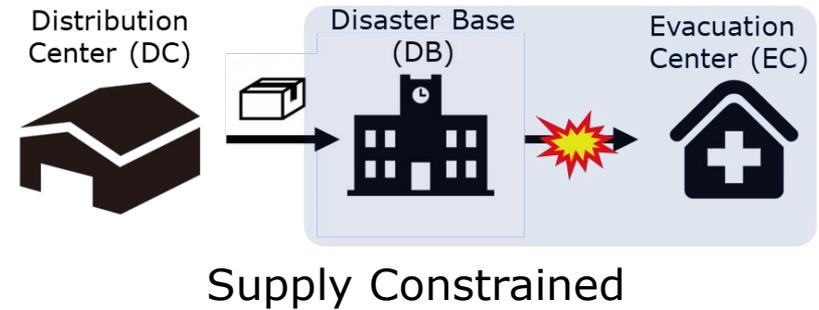
Focus

What preparations (e.g., staffing) should be done for the pull strategy?
 What is the efficient, cost-effective flow and storage in the pull strategy?

Challenges of Pull Strategy

(Almost) Perfect Information but **Supply Constrained**

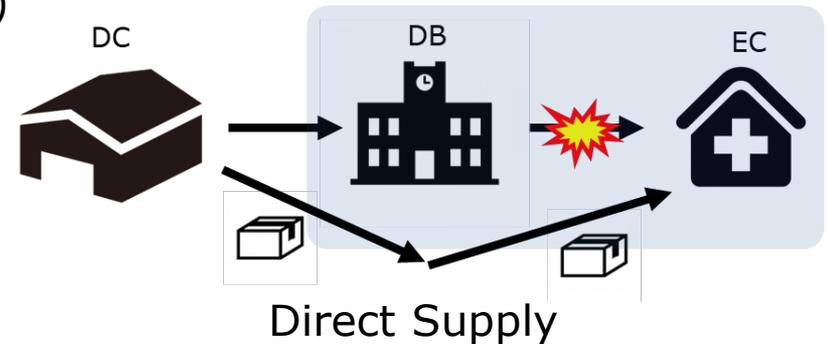
- In the Kumamoto Earthquakes, direct supply was the solution alternative.
- However, a large-scale disaster would also disrupt direct supply.



Observation (in the Kumamoto Earthquakes)

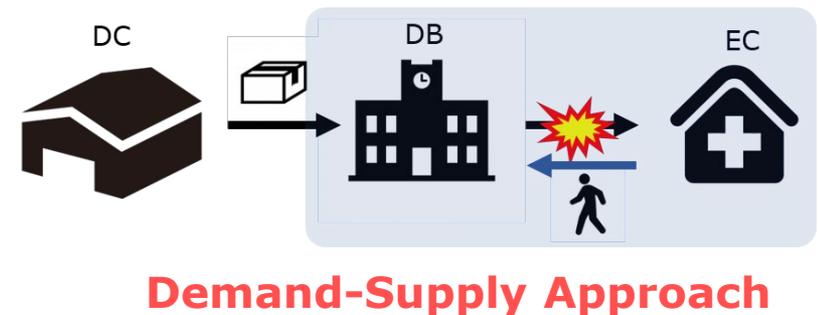
- **Some victims made trips** to acquire food and essential goods.

Suggest the potential for improvement through Demand-Supply Approach



Methodology

- Formulate an optimization problem for the demand-supply approach
- Numerical evaluate the performance of the approach



Previous Research

Previous models of network flow optimization for humans and goods

- discard **Queue Congestion** and **Inventory Congestion**.
- are **computationally inefficient**.

Typical Assumptions in Logistics Optimization

- ✓ Humans and Goods can move in **free-flow travel time (FFTT)**.
- ✓ Humans/goods are **serviced/consumed immediately on arrival**.

Previous Models Considering **Only Flow Congestion**, not Queue Congestion

- ✓ Muggy and Stamm (2020) formulate MPEC* s.t. congestion game.
- ✓ Gutjahr and Dzubur (2016) formulate BLPP s.t. optimal destination choice.

*Mathematical Programming with Equilibrium Constraints

**Bilevel Programming Problems

Previous Models Considering Queue Congestion

- ✓ Espejo-Díaz and Guerrero (2021), Fikar et al.(2018) present an agent-based simulation optimization framework.
- ✓ Limitation is **computational efficiency**.

Research Gap

- Optimal network flow for humans (traffic) and goods could attack HL problems, supply constraints.
- There is no optimization model to meet both **computationally efficient and queue congestion considerations**.

Research Objective

- Formulate an optimization problem that is (potentially) **computationally efficient** and describes **queue congestion**.
 - ✓ Propose BLPP
 - Upper: Optimize preparations (e.g., staffing, stockpiles)
 - Lower: Optimize dynamic network flow using Optimal Control Problem
- Numerical evaluate the performance of the **demand-supply approach**.
 - ✓ Show preliminary results on a simple network.

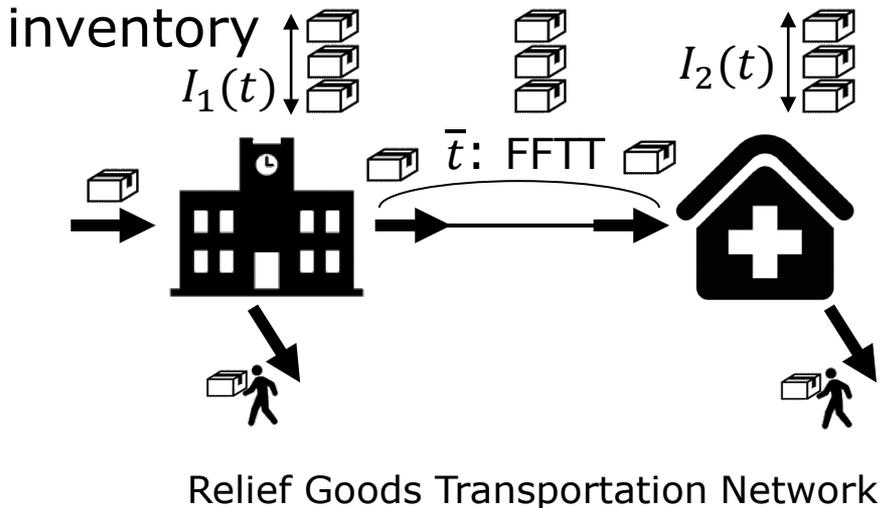


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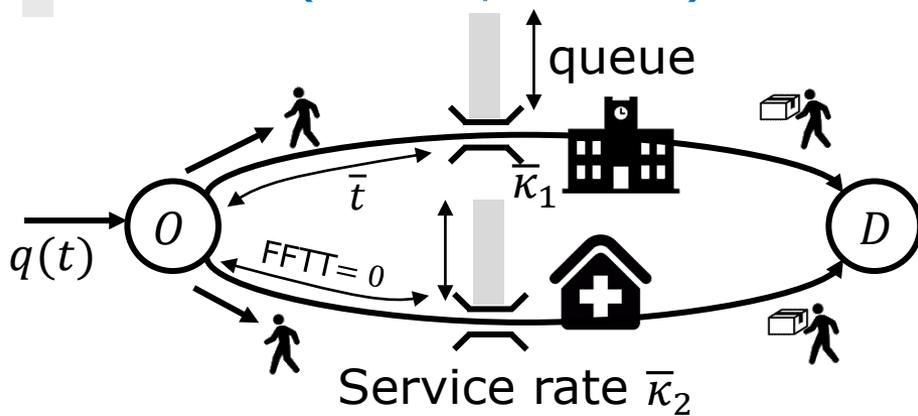
Modeling

Model Framework

Relief Goods



Human (Traffic, Victim)



A Parallel Link Network

- To minimize **queue congestion** and **inventory congestion**,
 - ✓ (Upper) Determine preparation strategies $\{I_1(0), I_2(0), \bar{\kappa}_1, \bar{\kappa}_2\}$ and
 - ✓ (Lower) Determine demand and supply dynamics.

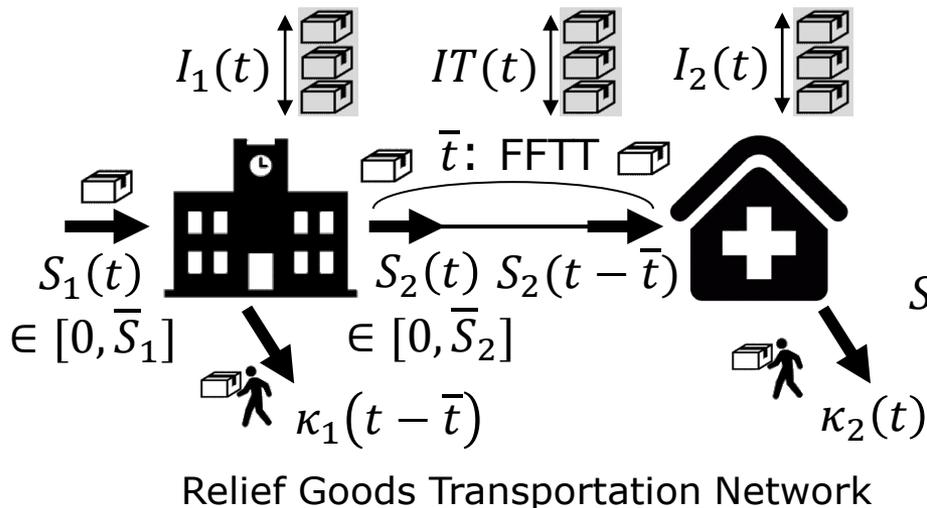
One victim needs only one item.

- (**Supply**) HOs supply DB, or supply EC via DB.
 - ✓ Between DB and EC, relief goods can move in FFTT.
- (**Demand**) Victims receive relief goods at DB or EC.
 - ✓ Between DB and EC, victims can move in FFTT.
 - ✓ Total relief demand for victims is uncertain. Denote the stochastic process as $Q(t)$ and the sample path as $q(t)$.

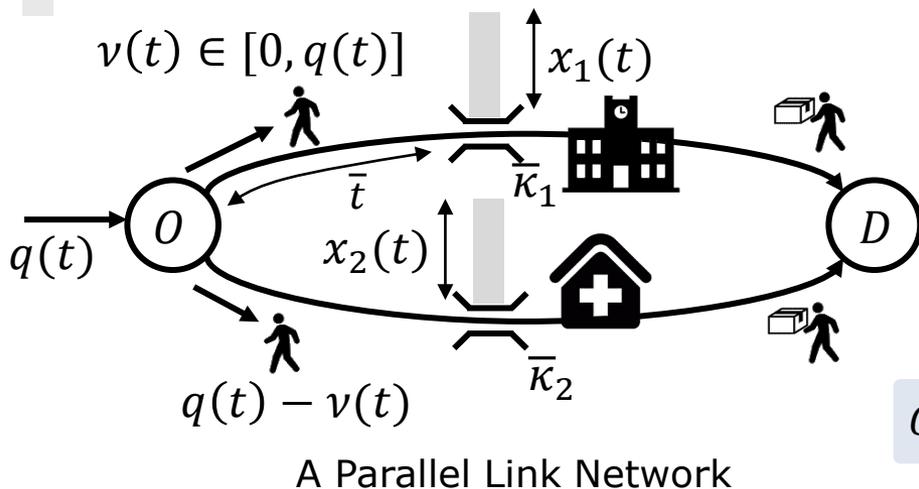
Variables

* an inventory if positive;
a shortage otherwise

Relief Goods (c.f. Kawase et al., 2019)



Human (c.f. Akamatsu and Nagae, 2007)



Stock (State Variables)

$I_1(t), I_2(t)$: Net inventory* at nodes

$IT(t)$: In-transit inventory

Flow (Control Variables)

$S_1(t)$: Inflow per unit-time at DB

$S_2(t)$: Outflow per unit-time at DB

$S_2(t - \bar{t})$: Inflow per unit-time at EC

$\kappa_1(t), \kappa_2(t)$: Demand per unit-time

One victim needs only one item.

Stock (State Variables)

$x_1(t), x_2(t)$: Queue

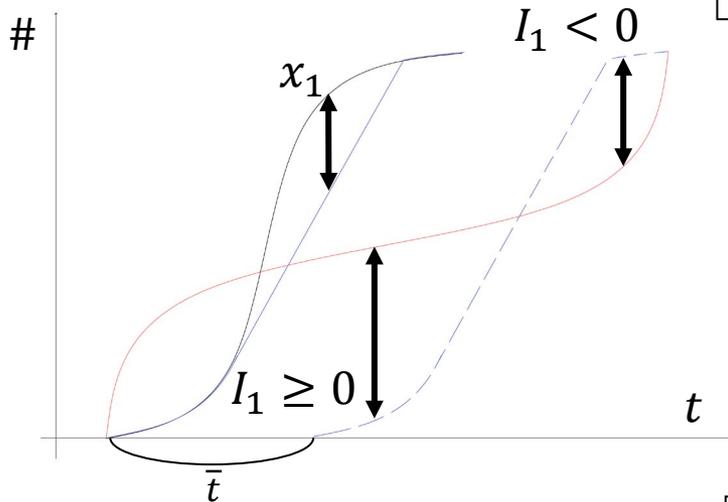
Flow (Control Variables)

$v(t)$: Inflow per unit-time to DB

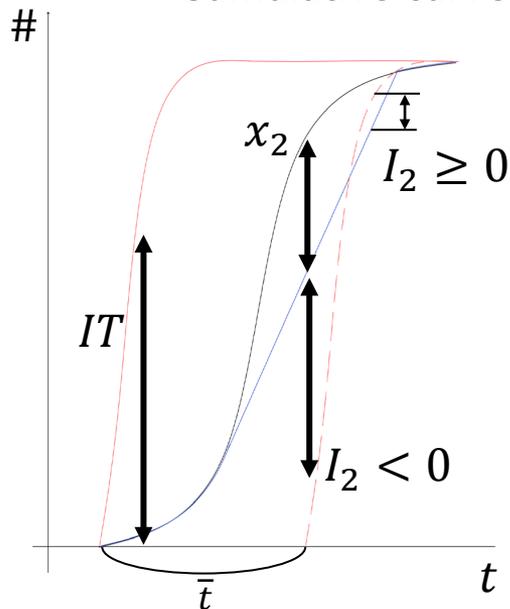
$\kappa_1(t), \kappa_2(t)$: Outflow per unit-time

O : Need relief goods D : Get relief goods

Dynamics



Cumulative curve at DB



Cumulative curve at EC

$$\begin{array}{ll}
 \text{---} & \int (S_1 - S_2)dt \\
 \text{---} & \int v dt \\
 \text{---} & \int \kappa_1 dt \\
 \text{- - -} & \int \kappa_1(t - \bar{t})dt
 \end{array}$$

$$dI_1/dt = S_1(t) - S_2(t) - \kappa_1(t - \bar{t}), \quad I_1(0) = I_{01} \quad (1)$$

$$dx_1/dt = v(t) - \kappa_1(t), \quad x_1(0) = 0 \quad (2)$$

$$\kappa_1(t) = \begin{cases} \bar{\kappa}_1 & \text{if } x_1(t) > 0 \\ \bar{\kappa}_1 & \text{if } x_1(t) = 0 \text{ and } v(t) \geq \bar{\kappa}_1 \\ v(t) & \text{if } x_1(t) = 0 \text{ and } v(t) < \bar{\kappa}_1 \end{cases} \quad (3)$$

$$\begin{array}{ll}
 \text{---} & \int S_2 dt \\
 \text{---} & \int (q - v)dt \\
 \text{- - -} & \int S_2(t - \bar{t})dt \\
 \text{---} & \int \kappa_2 dt
 \end{array}$$

$$dI_2/dt = S_2(t - \bar{t}) - \kappa_2(t), \quad I_2(0) = I_{02} \quad (4)$$

$$dIT/dt = S_2(t) - S_2(t - \bar{t}), \quad IT(0) = 0 \quad (5)$$

$$dx_2/dt = q(t) - v(t) - \kappa_2(t), \quad x_2(0) = 0 \quad (6)$$

$$\kappa_2(t) = \begin{cases} \bar{\kappa}_2 & \text{if } x_2(t) > 0 \\ \bar{\kappa}_2 & \text{if } x_2(t) = 0 \text{ and } q(t) - v(t) \geq \bar{\kappa}_2 \\ q(t) - v(t) & \text{if } x_2(t) = 0 \text{ and } q(t) - v(t) < \bar{\kappa}_2 \end{cases} \quad (7)$$

*(t) is omitted. 10

Cost

* This study assumes that the terminal cost $\phi(T)$ is 0.

Total Cost for a certain time horizon $[0, T]$ *

$$C = \int_0^T c(t) dt + \phi(T) \quad (8)$$

Increase in Total Cost per unit-time, $c(t)$

$$c(t) = c_{I_1}(t) + c_{I_2}(t) + c_{IT}(t) + c_{x_1}(t) + c_{x_2}(t) \quad (9)$$

Net Inventory Cost, $c_{I_1}(t) + c_{I_2}(t)$

$$c_{I_1}(t) = \max\{0, I_1(t)\} - \min\{0, I_1(t)\} \quad (10)$$

$$c_{I_2}(t) = \max\{0, I_2(t)\} - \min\{0, I_2(t)\} \quad (11)$$

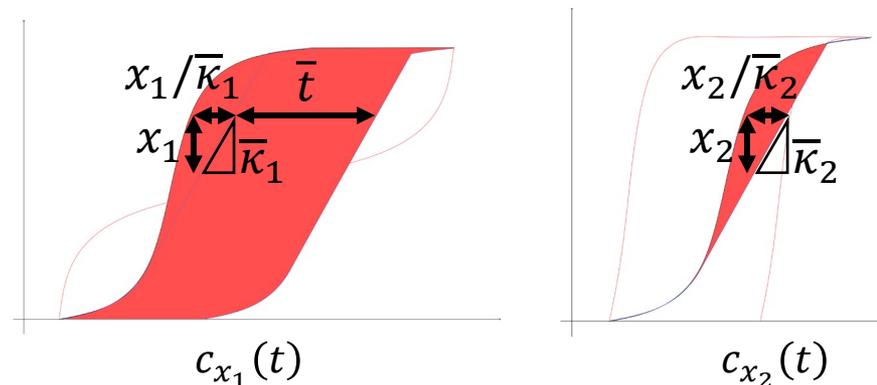
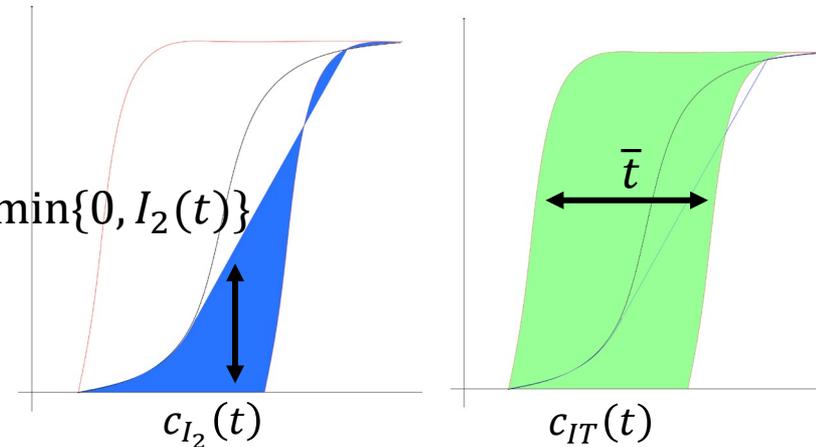
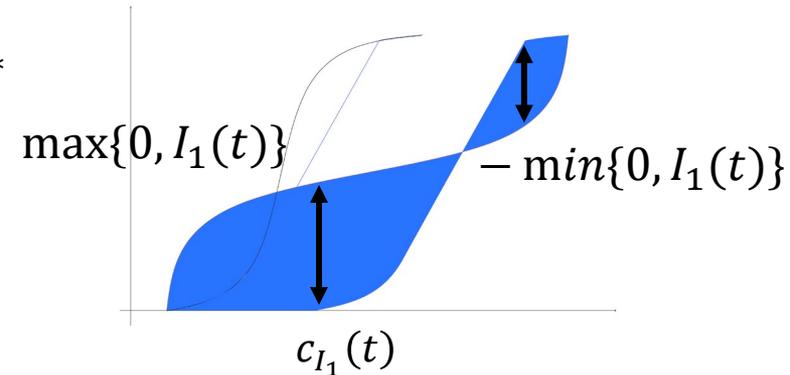
In-transit Inventory Cost, $c_{IT}(t)$

$$c_{IT}(t) = S_2(t) \cdot \bar{t} \quad (12)$$

Total Travel Time, $c_{x_1}(t) + c_{x_2}(t)$

$$c_{x_1}(t) = (x_1(t)/\bar{\kappa}_1 + \bar{t})v(t) \quad (13)$$

$$c_{x_2}(t) = x_2(t)/\bar{\kappa}_2(q(t) - v(t)) \quad (14)$$



Modified Cost

Problems involving delays are **not easy to solve**.

- Define modified cost \hat{C} so that the problem does not include delays.
- When $I_1(t) \geq 0$ and $I_2(t) \geq 0 \forall t \in [0, T]$, $C = \hat{C}$.

Modified Net Inventory Cost, $\hat{c}_{I_1}(t) + \hat{c}_{I_2}(t)$

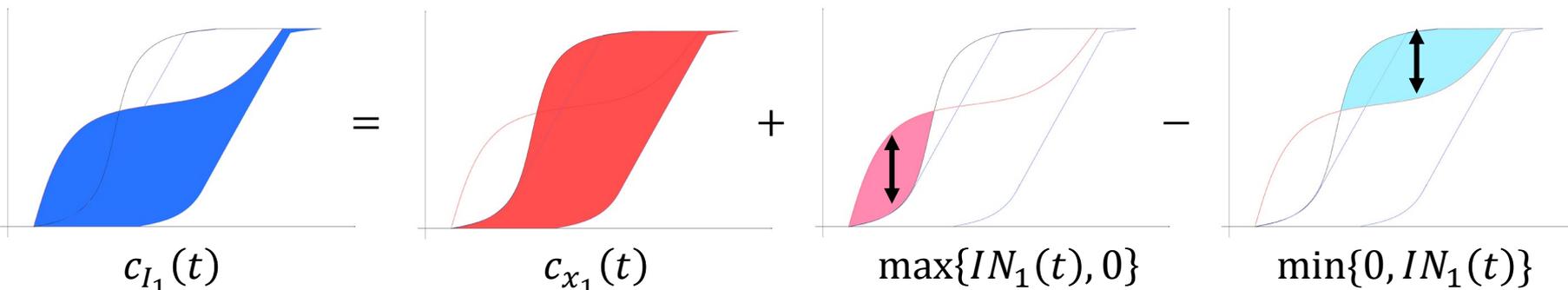
$$\hat{c}_{I_1}(t) = \max\{IN_1(t), 0\} - \min\{0, IN_1(t)\} + c_{x_1}(t) \quad (15)$$

$$\hat{c}_{I_2}(t) = IN_2(t) - c_{IT}(t) \quad (16)$$

$IN_1(t), IN_2(t)$: Potential Net inventory, including unarrived supply and demand

$$dIN_1/dt = S_1(t) - S_2(t) - v(t), \quad IN_1(0) = I_{01} \quad (17)$$

$$dIN_2/dt = S_2(t) - \kappa_2(t), \quad IN_2(0) = I_{02} \quad (18)$$



Bilevel Programming Problem

Lower-level: Linear Optimal Control Problem

$$\min_{\mathbf{X}, \mathbf{U}} [\hat{C} | I_{01}, I_{02}, \bar{\kappa}_1, \bar{\kappa}_2, \{q(t)\}]$$

s. t. Eq. (1) – (7), (12) – (18)

$$\hat{C} = \int_0^T \hat{c}(t) dt \quad \hat{c}(t) = \hat{c}_{I_1}(t) + \hat{c}_{I_2}(t) + c_{IT}(t) + c_{x_1}(t) + c_{x_2}(t)$$

$$\mathbf{X} := \{I_1(t), I_2(t), IN_1(t), IN_2(t), IT(t), x_1(t), x_2(t) | \forall t \in (0, T)\}$$

$$\mathbf{U} := \{S_1(t), S_2(t), v(t), \kappa_1(t), \kappa_2(t) | \forall t \in [0, T)\}$$

- Given preparation strategies $\{I_{01}, I_{02}, \bar{\kappa}_1, \bar{\kappa}_2\}$ and a demand sample path $\{q(t)\}$, the optimal control is obtained numerically.
- Apply existing computationally efficient solution method (c.f. Chavanasporn and Ewald, 2012) for linear optimal control problem.

Upper-level

$$\min_{I_{01}, I_{02}, \bar{\kappa}_1, \bar{\kappa}_2} E[\hat{C} | \mathbf{X}, \mathbf{U}] \quad \text{s. t.} \quad \text{Lower-level Problem and} \\ I_1(t) \geq 0, I_2(t) \geq 0, \bar{\kappa}_1 + \bar{\kappa}_2 = \bar{\kappa}, \{Q(t)\}$$

- Generate a finite number of sample paths $q(t)$ of stochastic process $Q(t)$
- Evaluate the expected total cost approximately
- Find the optimal $I_{01}, I_{02}, \bar{\kappa}_1, \bar{\kappa}_2$ in a brute-force fashion

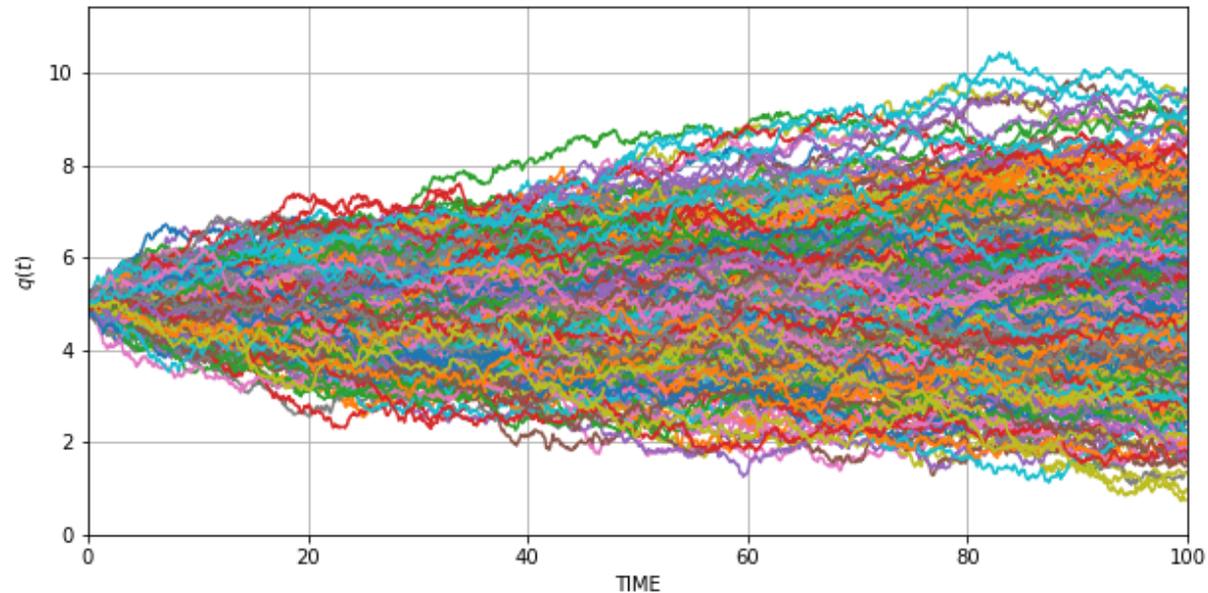


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Numerical Experiments

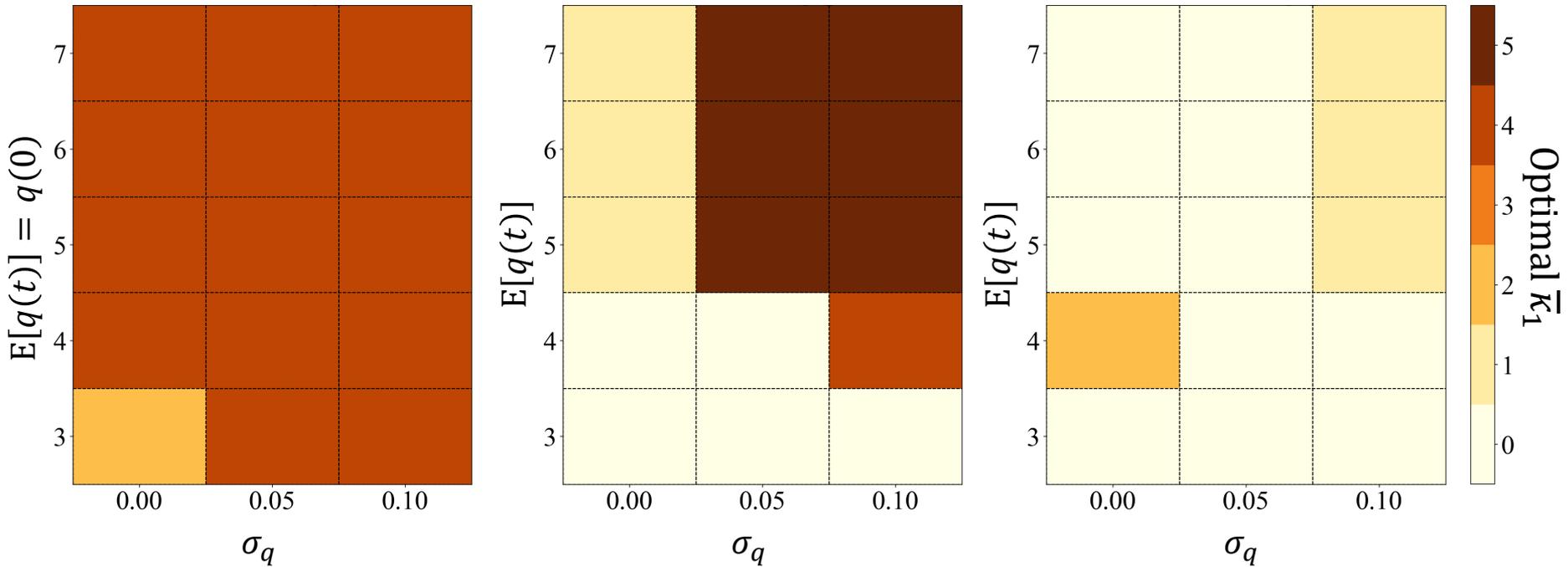
Numerical Experiments: Setting

- The number of sample paths $q(t)$ is 500.
- $dq(t) = \sigma_q dz(t)$, $z(t) \sim N(0, t)$, $q(0) = \{3, 4, 5, 6, 7\}$, $\sigma_q = \{0, 0.05, 0.1\}$
- $T = 100$
- FFTT, $\bar{t} = \{5, 10, 20\}$
- $\bar{S}_1 = 10, \bar{S}_2 = \{3, 5, 7\}$
- $\bar{\kappa} = 5, \bar{\kappa}_1 = \{0, 1, 2, 3, 4, 5\}$



500 Sample Paths ($q(0) = 5$, $\sigma_q = 0.05$, then $q(t) \sim N(q(0), \sigma_q^2 t)$)

Numerical Experiments: Result

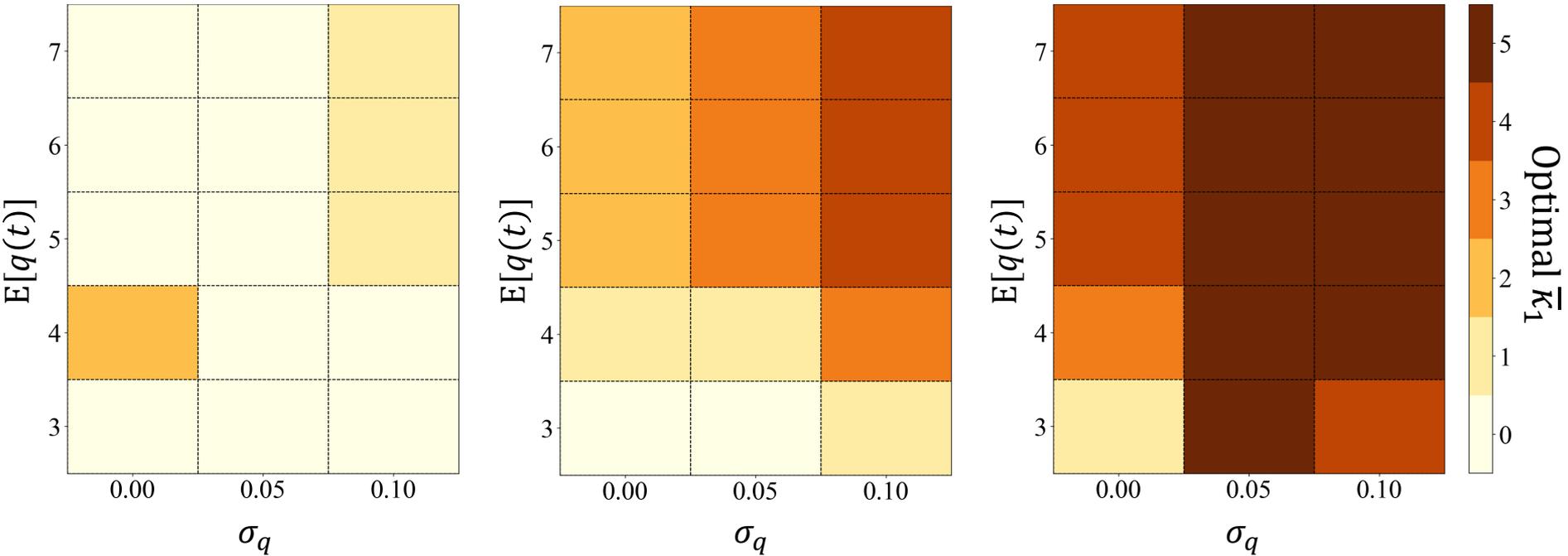


Optimal $\bar{\kappa}_1$ when FFTT $\bar{t} = 5$ (left: $\bar{S}_2 = 3$, center: $\bar{S}_2 = 5$, right: $\bar{S}_2 = 7$)

- The larger mean $E[q(t)]$ and variance $\sigma_q^2 t$ of demand increase optimal $\bar{\kappa}_1$.
- When supply constraint is relaxed ($\bar{S}_2 = 7$), optimal $\bar{\kappa}_1$ is likely to be 0.

Suggest that in a typical disaster situation ($E[q(t)]$, $\sigma_q^2 t$ are large, supply constraint is tight), optimal $\bar{\kappa}_1 > 0$ (i.e., demand-supply approach is effective). 16

Numerical Experiments: Result



Optimal $\bar{\kappa}_1$ when $\bar{S}_2 = 7$ (left: FFTT $\bar{t} = 5$, center: $\bar{t} = 10$, right: $\bar{t} = 20$)

- FFTT \bar{t} between DB and EC increases, then
 - ✓ optimal $\bar{\kappa}_1$ tends to increase, and
 - ✓ the ratio of users' cost (total travel time for victims) increase.
 - ✓ Non-negative constraints on $I_1(t)$ and $I_2(t)$ could be causing supply-side costs to be greater than optimum.

■ Formulation

- ✓ Formulate BLPP to **evaluate the performance of demand-supply approach**
 - Upper: Optimize preparations (e.g., staffing, stockpiles)
 - Lower: Optimize dynamic network flow for humans and goods
- ✓ Reformulate lower-level one as a **(non-delayed) optimal control problem by modifying net inventory cost**

■ Numerical Experiments

- ✓ **Demand-supply approach would be effective in a typical disaster situation.**
- ✓ However, the proposed model is likely to overestimate supply-side costs. The optimality of the reformulated problem, optimal control problem, should be evaluated.

Case Studies

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Network flow optimization for humans and goods

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Optimal Control Problem

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