



名古屋大学
NAGOYA UNIVERSITY

Yokohama.. Future Compact City

Team J

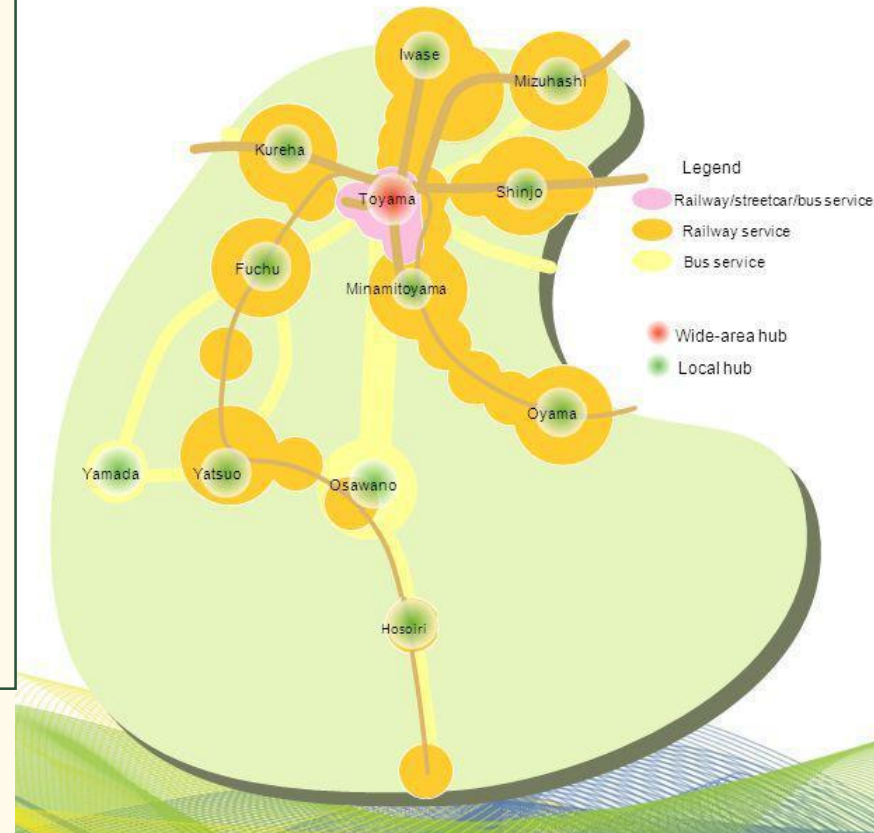
Khan
Trang
Xiong
Zamzam

What is Compact City?

Compact city:

- ✓ High residential density with mixed land use
- ✓ Better mobility
- ✓ Less impact on environment

Compact City model in Toyama

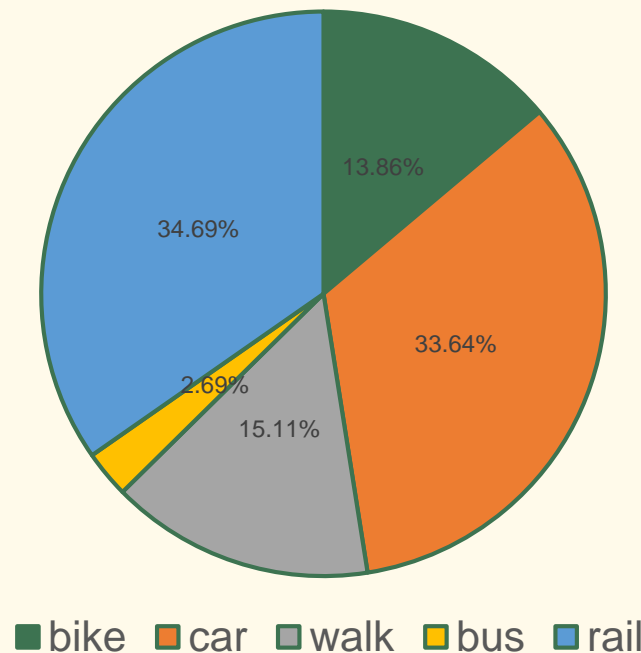


- Renovation of public transportation to reduce auto-dependency
- Incentives to concentrate activities in the target areas

Why Compact city in Yokohama?

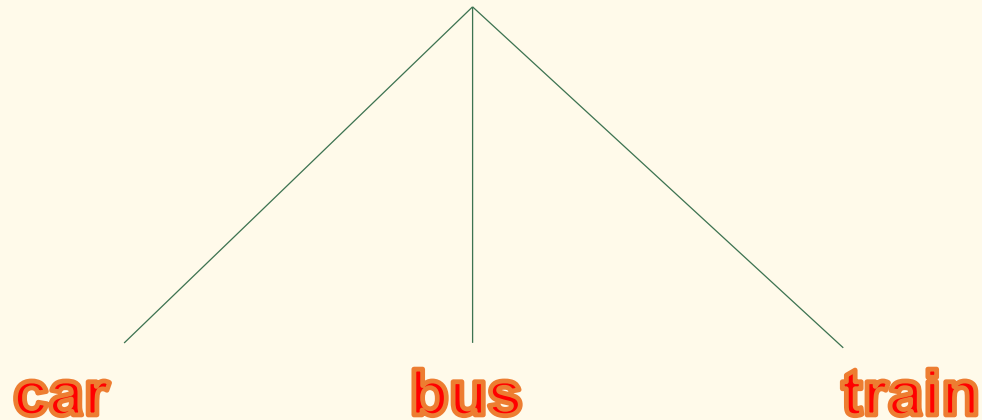
- **Population:** Over 3.7 million
- **Area:** over 168 square miles,
- **Density:** 22,103 people per square mile

Mode Share in Yokohama City



Mode Estimation

- **Model 1:** Less than 10 km
- **Model 2:** More than 10 km
- **Aim:** To investigate how the distance would affect mode choice



Model Estimation

$$V_R = \beta_1 + \beta_3 Ac_R + \varepsilon_R$$

$$V_B = \beta_2 + \beta_4 Ac_B + \varepsilon_B$$

$$V_C = \beta_4 Ac_B + \beta_5 Td + \varepsilon_C$$

- R : rail
- B : bus
- C : car
- Ac : Access time
- Td : Trip duration

Estimation Result

```
RGui (32-bit) - [R Console]
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[Icons]

> Data <- read.table("C:/Users/Phan Thu Trang/Downloads/Summer school 2018/Long distance.txt")
> colnames(Data) <- c("Mode_choice", "Trip_duration", "Avail_R", "Access_R", "Avail_B", "Access_B")
> ## Count the number of data rows
> hh <- nrow(Data)
> ## Set the initial values of the parameters (the number in parenthesis corresponds to the number of parameters to be estimated)
> b0 <- numeric(4)
> b0 <- c(1,1,1,1)
> ## Recall that we estimate parameters by maximizing the log-likelihood function, hence we first need to define that function
>
> ##### Define the log-likelihood function of the logit model#####
>
> fr <- function(x) {
+
+   ## declare the log-likelihood variable, set value to 0
+   LL = 0
+
+   ### For this choice problem, we consider the following 3 modes
+   ## rail
+   ## bus
+   ## car
+
+   ## calculate the utility function: :introduce the desired explanatory variables in the function
+
+   train <- Data$Avail_R * exp(x[1]*matrix(1,nrow = hh,ncol = 1)+ x[3] * Data$Access_R)
+   bus <- Data$Avail_B * exp(x[2]*matrix(1,nrow = hh,ncol = 1)+ x[3] * Data$Access_B)
+   car <- exp(x[3] * Data$Access_B + x[4] * Data$Trip_duration)
+   ### Calculate the choice probabilities
+   ## calculate the Inclusive Value (the denominator of the choice probabilities equation)
+   deno <- (car + train + bus)
+
+   ## Calculate individual choice probabilities
+   Ptrain <- Data$Avail_R * (train / deno)
+   Pbus <- Data$Avail_B * (bus / deno)
+   Pcar <- 1 * (car / deno)
+
+   ## Avoid problems stemming from choice probabilities becoming zero.
+   Ptrain <- (Ptrain !=0) * Ptrain + (Ptrain == 0)
+   Pbus <- (Pbus !=0) * Pbus + (Pbus == 0)
+   Pcar <- (Pcar !=0) * Pcar + (Pcar == 0)
+
+   ## Choice results
+ }
```

Estimation Result

```
RGui (32-bit) - [R Console]
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+ ## Choice results
+ Ctrain <- Data$Mode_choice == 200
+ Cbus <- Data$Mode_choice == 240
+ Ccar <- Data$Mode_choice == 100
+
+ ## Calculate the Log-likelihood function
+ LL <- colSums(Ctrain*log(Ptrain) + Cbus*log(Pbus) + Ccar *log(Pcar))
+ return(LL)
+ }
> ##### Maximize the Log-likelihood function#####
>
> ##Parameter optimization
> res <- optim(b0,fr,gr=NULL, method = "Nelder-Mead", hessian = TRUE, control=list(fnscale=-1))
Error in optim(b0, fr, gr = NULL, method = "Nelder-Mead", hessian = TRUE, :
function cannot be evaluated at initial parameters
>
> ## Parameters and Hessian matrix calculation
> b <- res$par
Error: object 'res' not found
> hhh <- res$hessian
Error: object 'res' not found
>
> ## Calculate the t-statistic
> tval <- b/sqrt(-diag(solve(hhh)))
Error: object 'b' not found
>
> ## L(0), Log-Likelihood when all parameters are 0
> L0 <- fr(b0)
> ## LL, maximum likelihood
> LL <- res$value
Error: object 'res' not found
>
> ##### Output #####
> print(res)
Error in print(res) : object 'res' not found
> ## t-statistic
> print(tval)
Error in print(tval) : object 'tval' not found
> ## L(0)
> print(L0)
[1] NA
```

Policy Simulation

- Compact City policies:

- Public-Private Partnership
- Urban growth boundary (contain outward growth)
- Polycentric compact city pattern

